

The copula-graphic estimator in censored nonparametric location-scale regression models

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Outline

- 1 Introduction
 - Motivating example
 - Model
 - Goal
- 2 Estimation
- 3 Further research

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Motivating example

Consider data on survival times of patients after heart transplantation,

- Y = time until death (caused from heart failure)
- C = time until death (caused from other reasons)
- X = age of a patient

we observe:

- $T = \min(Y, C)$
- $\Delta = \mathbf{1}(Y < C)$
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Model

Consider the model:

- $(T_i = \min(Y_i, C_i), X_i, \Delta_i)$ are iid vectors

$$Y = m(X) + \sigma(X)\varepsilon$$

- $m(X)$ = location functional
- $\sigma(X)$ = scale functional
- $X \perp\!\!\!\perp \varepsilon$
- Y and C are Copula dependent

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- Y and C are Copula dependent

Survival time Y and censoring time C are copula dependent i.e.

$\forall x$ there is function C_x such that,

$$P(Y > y, C > c | X = x) = C_x(\bar{F}(y|x), \bar{G}(c|x))$$

where

- $\bar{F}(y|x) = P(Y > y | X = x)$
- $\bar{G}(c|x) = P(C > c | X = x)$
- C_x is Archimedean Copula, i.e.
there exist generating function $\phi_x(\cdot)$ s.t.
 $C_x(u, v) = \phi_x^{-1}(\phi_x(u) + \phi_x(v))$

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Goal

Find estimator for $F(y|x) = P(Y \leq y|X = x)$

Our assumptions:

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- $P(Y > y, C > c|X = x) = C_x(\bar{F}(y|x), \bar{G}(c|x))$

Previous work:

Van Keilegom and Akritas, 1999

- $Y = m(X) + \sigma(X)\varepsilon$, $X \perp\!\!\!\perp \varepsilon$
- For given X , $Y \perp\!\!\!\perp C$

Braekers and Veraverbeke, 2005

- Relation between X and Y is completely nonparametric
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Estimation

For simplicity reasons assume that $\sigma(x) = 1$

$$Y = m(X) + \varepsilon$$

Find estimator for $\bar{F}(y|x) = P(Y > y|X = x)$

We can show that

$$\bar{F}(y|x) = \bar{F}_e(y - m(x))$$

where $\bar{F}_e(y) = P(\varepsilon > y)$

We will estimate $\bar{F}(y|x)$ by estimating $\bar{F}_e(\cdot)$ and $m(\cdot)$

$$\hat{F}(y|x) = \hat{F}_e(y - \hat{m}(x))$$

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Estimate error distribution $\bar{F}_e(y) = P(\varepsilon > y)$

Using notation

- $T = \min(Y, C)$
- $\bar{G}_e(c|x) = P(C - m(X) > c|X = x)$
- $\bar{H}_e(y|x) = P(T - m(X) > y|X = x)$

we can get

- $\bar{H}_e(y|x) = \phi_x^{-1}(\phi_x(\bar{F}_e(y)) + \phi_x(\bar{G}_e(y|x)))$

Now by applying ϕ_x on both sides and integrating them with respect to dF_X we get

- $\int \phi_x(\bar{H}_e(y|x))dF_X(x) = \phi(\bar{F}_e(y)) + \int \phi_x(\bar{G}_e(y|x))dF_X(x)$ (1)

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Find estimator $\hat{F}_e(\cdot)$ that solves equation (1) and is

- right continuous
- step functions
- have jumps at the points $T_i - m(X_i)$ for $\Delta_i = 1$

Assuming that $\bar{G}_e(\cdot)$ satisfies

- $\bar{G}_e(T_i - m(X_i)) = \bar{G}_e((T_i - m(X_i))^-), \forall \Delta_i = 1$

we can get explicit form of $\hat{F}_e(\cdot)$

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$$\hat{F}_e(y) = \phi^{-1} \left\{ - \sum_{\substack{T_i - m(X_i) \leq y \\ \Delta_i = 1}} \int [\phi_x(\bar{H}_e((T_i - m(X_i))^- | x)) - \phi_x(\bar{H}_e(T_i - m(X_i) | x))] dF_X(x) \right\}$$

- $F_X(x) = P(X \leq x)$

$$\hat{F}_X(x) = \frac{1}{n} \sum_{i=1}^n \mathbb{1}_{\{X_i \leq x\}}$$

- $\phi(u) = \int \phi_x(u) dF_X(x)$

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$$m(x) = \int_0^1 F^{-1}(s|x)J(s)ds$$

where

- $\int_0^1 J(s)ds = 1$
- $J(s) \geq 0$

We will estimate $\hat{m}(\cdot)$ by plugging in pre-estimator $\tilde{F}(\cdot|x)$ which is modification of Braekers and Veraverbeke, 2005.

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Outline

- 1 Introduction
 - Motivating example
 - Model
 - Goal

- 2 Estimation

- 3 Further research

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- show asymptotical normality of estimator
- study estimator's characteristics via simulations
- study estimator's characteristics via theory
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